



Uncertainty reasoning and machine learning Introduction to notions of calibrated and valid predictions

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Uncertainty Reasoning and Machine Learning



A predictive system

 perceives a training data set (consisting of input-output pairs which specify individuals of a population) and a hypothesis space (consisting of the possible classifiers),







A predictive system

- perceives a training data set (consisting of input-output pairs which specify individuals of a population) and a hypothesis space (consisting of the possible classifiers),
- and seeks a classifier that optimizes its chance of making accurate predictions with respect to some given evaluation criterion (which is typically a loss function or an accuracy metric) which reflects how good/bad the predictive system is.







Optimization problem should be described after declaring

- a training (+ validation) data set,
- a hypothesis space,
- an evaluation criterion,
- and a notion of an optimal classifier.







Optimization Problem: "Spam in Emails" Example

What optimization problem do you want to solve?

• Using a decision tree to predict "Spam in Emails"







Optimization Problem: "Cat Dog classification" Example

What optimization problem do you want to solve?

• Using a convolutional neural network (CNN) to predict images as either a cat or a dog









After this lecture students should be able to

- describe commonly used notions of classifier calibration [10]
- describe a few calibration errors and calibration methods [10]
- describe commonly used notions of coverage [1]
- describe a few coverage metrics and conformal procedures [1]





Outline



Classifier Calibration

- \circ Introduction
- \circ Notions
- Calibration Errors
- Post-hoc Calibration
- o Other methods
- Conformal Prediction







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A Weather Forecasting Example









A Weather Forecasting Example



- Forecaster: "the probability of rain tomorrow in Compiègne is 80%"
- How could we interpret this forecast?







A Weather Forecasting Example (cont.)

- On about 80% of the days when the whether conditions are like tomorrow's, you would experience rain in Compiègne?
- It will rain in 80% of the land area of Compiègne?
- It will rain in 80% of the time?







A Weather Forecasting Example (cont.)

- On about 80% of the days when the whether conditions are like tomorrow's, you would experience rain in Compiègne?
- It will rain in 80% of the land area of Compiègne?
- It will rain in 80% of the time?

Determining the degree to which a forecaster is well-calibrated

- cannot be done on a per-forecast basis,
- but requires looking at a sufficiently large and diverse set of forecasts.







Why Calibration Matters?

A well-calibrated classifier is expected to

 generate estimated class probabilities, which are consistent with what would naturally occur.







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A well-calibrated classifier is expected to

- generate estimated class probabilities, which are consistent with what would naturally occur.
- If (heterogeneous) classifiers can be well-calibrated,
 - their estimated class probabilities may be of the same "scale" and may be combined
 - they can be further compared given the same/similar levels of predictive performance.







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Notions of Calibration (Mentioned in Lecture 3)

Confidence calibration [3]:

$$P(y = \arg \max_{y \in \mathscr{Y}} \theta_y | \boldsymbol{x} \text{ such that } \max_{y \in \mathscr{Y}} \theta_y | \boldsymbol{x} = \beta) = \beta, \forall \beta \in [0, 1].$$
(1)







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(1)

Classwise calibration [12]:

$$P(y \text{ such that } \theta_y | \boldsymbol{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].$$
(2)

• May be harder to ensure, compared to confidence calibration







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(2)

• May be harder to ensure, compared to **confidence calibration Distribution calibration** [4]:

$$P(y \text{ such that } \boldsymbol{\theta} | \boldsymbol{x} = \boldsymbol{q}) = \boldsymbol{q}, \forall \boldsymbol{q} \in \triangle^{|\mathcal{Y}|}, \qquad (3)$$

where $\Delta^{|\mathscr{Y}|}$ is the $|\mathscr{Y}|\text{-dimensional simplex}$

• May be harder to ensure, compared to the **above notions**.





Notions of Calibration with Examples



(a) Underconfidence

(b) Overconfidence

(c) Calibrated classifier

Confidence calibration: Examples [2]







Notions of Calibration with Examples (Exercise 1)

Basic setup (rephrased from an example in [10]):

- A dataset contains 40 instances
- A model *h* which partitions the input space into 4 regions:

# instances	Predicted probabilities	Class distributions
10	(0.3,0.3,0.4)	(4,2,4)
10	(0.4,0.3,0.3)	(3,4,3)
10	(0.4,0.6,0.0)	(5,5,0)
10	(0.3,0.6,0.1)	(2,7,1)





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10	(0.3,0.6,0.1)	(2,7,1)

Question: Check if the following statements are correct

- h is not confidence-calibrated
- *h* is classwise-calibrated
- h is not distribution-calibrated





Basic setup (rephrased from an example in [10]):

# instances	Predicted probabilities	Class distributions
10	(0.3,0.3, 0.4)	(4,2,4)
10	(0.4 ,0.3,0.3)	(3,4,3)
10	(0.4, 0.6 ,0.0)	(5,5,0)
10	(0.3, 0.6 ,0.1)	(2,7,1)

Statement: h is not confidence-calibrated

$$P(y = \arg\max_{y \in \mathscr{Y}} \theta_y | \boldsymbol{x} \text{ such that } \max_{y \in \mathscr{Y}} \theta_y | \boldsymbol{x} = \beta) = \beta, \forall \beta \in [0, 1].$$
(4)

•
$$\beta = 0.4$$
: $P = (4+3)/20 = 7/20 \neq 0.4$

• $\beta = 0.6$: $P = (5+7)/20 = \frac{12}{20} = 0.6$







Notions of Calibration with Examples (Solution 1.2)

Basic setup (rephrased from an example in [10]):

# Instances	Predicted probabilities	Class distributions
10	(0.3,0.3,0.4)	(4,2,4)
10	(0.4,0.3,0.3)	(3,4,3)
10	(0.4,0.6,0.0)	(5,5,0)
10	(0.3,0.6,0.1)	(2,7,1)

Statement: h is classwise-calibrated

$$P(y \text{ such that } \theta_y | \mathbf{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].$$
(5)

•
$$y_1 \wedge \beta_1 = 0.3$$
: $P = (2+4)/20 = 0.3$,

•
$$y_2 \wedge \beta_2 = 0.3$$
: $P = (2+4)/20 = 0.3$,

•
$$y_3 \wedge \beta_3 = 0.4$$
: $P = 4/10 = 0.4$,

•
$$y_3 \wedge \beta_3 = 0.0$$
: $P = 0/10 = 0.0$,

$$y_1 \wedge \beta_1 = 0.4$$
: $P = (3+5)/20 = 0.4$
 $y_2 \wedge \beta_2 = 0.6$: $P = (5+7)/20 = 0.6$
 $y_3 \wedge \beta_3 = 0.3$: $P = 3/10 = 0.3$
 $y_3 \wedge \beta_3 = 0.1$: $P = 1/10 = 0.1$





Notions of Calibration with Examples (Solution 1.3)

Basic setup (rephrased from an example in [10]):

# Instances	Predicted probabilities	Class distributions
10	(0.3,0.3,0.4)	(4,2,4)
10	(0.4,0.3,0.3)	(3,4,3)
10	(0.4,0.6,0.0)	(5,5,0)
10	(0.3,0.6,0.1)	(2,7,1)

Statement: h is not distribution-calibrated

$$P(y \text{ such that } \boldsymbol{\theta} | \boldsymbol{x} = \boldsymbol{q}) = \boldsymbol{q}, \forall \boldsymbol{q} \in \triangle^{|\mathscr{Y}|}, \qquad (6)$$

•
$$\boldsymbol{q} = (0.3, 0.3, 0.4)$$
: $\boldsymbol{P} = (4/10, 2/10, 4/10) = (0.4, 0.2, 0.4) \neq (0.3, 0.3, 0.4)$

- $\boldsymbol{q} = (0.4, 0.3, 0.3)$: $P = (3/10, 4/10, 3/10) = (0.3, 0.4, 0.3) \neq (0.4, 0.3, 0.3)$
- $\boldsymbol{q} = (0.4, 0.6, 0.0)$: $P = (5/10, 5/10, 0/10) = (0.5, 0.5, 0.0) \neq (0.4, 0.6, 0.0)$
- $\boldsymbol{q} = (0.3, 0.6, 0.1)$: $P = (2/10, 7/10, 1/10) = (0.2, 0.7, 0.1) \neq (0.3, 0.6, 0.1)$





A Note on Classifier Calibration (Exercise 2)

Consider three notions of classifier calibration:

• Confidence calibration [3]:

 $P(y = \arg\max_{y \in \mathscr{Y}} \theta_{y} | \boldsymbol{x} \text{ such that } \max_{y \in \mathscr{Y}} \theta_{y} | \boldsymbol{x} = \beta) = \beta, \forall \beta \in [0, 1].$ (7)

• Classwise calibration [12]:

$$P(y \text{ such that } \theta_y | \boldsymbol{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].$$
(8)

• Distribution calibration [4]:

$$P(y \text{ such that } \boldsymbol{\theta} | \boldsymbol{x} = \boldsymbol{q}) = \boldsymbol{q}, \forall \boldsymbol{q} \in \triangle^{|\mathscr{Y}|}, \qquad (9)$$

where $\Delta^{|\mathscr{Y}|}$ is the $|\mathscr{Y}|$ -dimensional simplex.

Prove that these notions are equivalent for binary classification?





A Note on Classifier Calibration (Exercise 3)

Consider three notions of classifier calibration:

• Confidence calibration [3]:

 $P(y = \arg\max_{y \in \mathscr{Y}} \theta_{y} | \boldsymbol{x} \text{ such that } \max_{y \in \mathscr{Y}} \theta_{y} | \boldsymbol{x} = \beta) = \beta, \forall \beta \in [0, 1].$ (10)

• Classwise calibration [12]:

$$P(y \text{ such that } \theta_y | \mathbf{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].$$
(11)

• Distribution calibration [4]:

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where $\Delta^{|\mathscr{Y}|}$ is the $|\mathscr{Y}|$ -dimensional simplex.

Prove that $h(\mathbf{x}) = P(\mathcal{Y}), \forall \mathbf{x}$, is perfectly calibrated?





Notes on Classifier Calibration (Cont.)

Comments on confidence/classwise/distribution calibration:

- Well-calibrated classifiers may perform poorly.
- Using calibration error as the only criterion to assess classifiers might not be a good idea ...
- Well-calibrated and accurate classifiers would be useful in practice!
- They would be seen as notions of marginal calibration ← population level







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- Other methods
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Calibration Error: The Binary Case

Binary estimated calibration error (Binary-ECE):

- Specify a number *M* of bins
- Apply equal-width binning to $\theta_1 | \boldsymbol{x}$ on **D**
- For each bin B_m, compute average probability s
 ^(Bm) and the proportion of positives y
 ^(Bm)

$$\overline{s}(\mathbf{B}_m) = \frac{1}{|\mathbf{B}_m|} \sum_{\mathbf{x} \in \mathbf{B}_m} \theta_1 |\mathbf{x}$$
$$\overline{y}(\mathbf{B}_m) = \frac{1}{|\mathbf{B}_m|} \sum_{\mathbf{x} \in \mathbf{B}_m} y$$

Compute Binary-ECE

Binary-ECE(**D**) =
$$\sum_{m=1}^{M} \frac{|\mathbf{B}_m|}{|\mathbf{D}|} |\overline{y}(\mathbf{B}_m) - \overline{s}(\mathbf{B}_m)|$$





Calibration Error: The Binary Case (Exercise 4)

Basic setup:

- A given data set $\mathbf{D} = \{(\mathbf{x}_n, y_n) | n = 1, \dots, N\}$ with $y \in \{0, 1\}$
- The proportion of instances with y = 1 is $0.5 + \epsilon$
- The decision rule is 0/1 loss ℓ and the number of bins is 10

Questions:

Show that there is at least one classifier with

Binary-ECE(**D**) = 0.0 and
$$\frac{1}{N} \sum_{n=1}^{N} \ell(y_n^*, y_n) = 0.0$$







Calibration Error: The Binary Case (Exercise 4)

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· Show that there is at least one classifier with

Binary-ECE(**D**) = 0.0 and
$$\frac{1}{N} \sum_{n=1}^{N} \ell(y_n^*, y_n) = 0.5 - \epsilon$$







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• Can we find worse perfectly calibrated classifiers?





Calibration Error: The Binary Case (Exercise 5)

Basic setup:

- A given data set $\mathbf{D} = \{(\mathbf{x}_n, y_n) | n = 1, \dots, N\}$ with $y \in \{0, 1\}$
- The proportion of instances with y = 1 is $\alpha \neq 0.5$
- The decision rule is 0/1 loss ℓ and the number of bins is M

Questions:

Show that there is at least one classifier with

Binary-ECE(**D**) = 0.0 and
$$\frac{1}{N} \sum_{n=1}^{N} \ell(y_n^*, y_n) = 0.0$$






Calibration Error: The Binary Case (Exercise 5)

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Show that there is at least one classifier with

Binary-ECE(**D**) = 0.0 and
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Binary-ECE(**D**) = 0.0 and
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Can we find worse perfectly calibrated classifiers?





Classwise Calibration Error

Estimated classwise calibration error (classwise-ECE):

- For each class $y \in \mathcal{Y}$, consider y as class 1 and the others as 0
- Compute Binary-ECE for class $y \in \mathscr{Y} \longrightarrow$ Binary-ECE_y(**D**)
- Compute classwise-ECE

classwise-ECE(
$$\mathbf{D}$$
) = $\frac{1}{|\mathscr{Y}|} \sum_{y \in \mathscr{Y}} \text{Binary-ECE}_{y}(\mathbf{D})$







Classwise Calibration Error (Exercise 6)

Basic setup:

- A given data set $\mathbf{D} = \{(\mathbf{x}_n, y_n) | n = 1, ..., N\}$ with $y \in \{0, 1, 2\}$
- The proportions of instances with (y = 0, y = 1, y = 2) are $(\alpha_0, \alpha_1, \alpha_2)$
- The decision rule is 0/1 loss ℓ and the number of bins is M

Questions:

Can we find at least one classifier with

classwise-ECE(**D**) = 0.0 and
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Questions:

· Can we find at least one classifier with

classwise-ECE(**D**) = 0.0 and
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· Show that there is at least one classifier with

classwise-ECE(**D**) = 0.0 and
$$\frac{1}{N} \sum_{n=1}^{N} \ell(y_n^*, y_n) = 1 - \max(\alpha_0, \alpha_1, \alpha_2)$$







Classwise Calibration Error (Exercise 6)

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Confidence Calibration Error

Confidence-ECE is the weighted average difference between accuracy and average confidence across all bins:

Confidence-ECE(**D**) =
$$\sum_{m=1}^{M} \frac{|\mathbf{B}_m|}{|\mathbf{D}|} |\operatorname{accuracy}(\mathbf{B}_m) - \operatorname{confidence}(\mathbf{B}_m)|$$
 (13)

- accuracy(**B**_m): Average accuracy in bin **B**_m
- confidence(**B**_m): Average confidence in bin **B**_m







Confidence Calibration Error (Exercise 7)

Basic setup:

- A given data set $\mathbf{D} = \{(\mathbf{x}_n, y_n) | n = 1, ..., N\}$ with $y \in \{0, 1, 2\}$
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Questions:

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Confidence Calibration Error (Exercise 7)

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Questions:

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· Show that there is at least one classifier with

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Confidence Calibration Error (Exercise 7)

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Can we find worse perfectly calibrated classifiers?





Notes on Classifier Errors (Homework)

Basic setup:

- Choose some calibration error
- Choose your favorite classifier
- · Choose one data set you want to work with







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Basic setup:

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- Choose your favorite classifier
- · Choose one data set you want to work with

Compute & compare:

- Train your favorite classifier
- Do post-hoc calibration (see next slides)
- Compute the calibration error







Notes on Classifier Errors (Homework)

Basic setup:

- Choose some calibration error
- Choose your favorite classifier
- · Choose one data set you want to work with

Compute & compare:

- Train your favorite classifier
- Do post-hoc calibration (see next slides)
- Compute the calibration error
- Estimate the prior distribution $P(\mathscr{Y})$ using MLE and/or DM
- Use $h(\mathbf{x}) = P(\mathcal{Y}), \forall \mathbf{x}$
- Compute the calibration error





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How to learn well-calibrated and accurate classifiers¹?



¹I would be rich if I knew a very good answer :)



How to learn well-calibrated and accurate classifiers¹?

Learn a well-calibrated classifier (a good strategy?)

- Basic setup: A hypothesis space (classifiers) and a calibration error
- Problem: Find a classifier which optimizes the calibration error



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How to learn well-calibrated and accurate classifiers¹?

Learn a well-calibrated classifier (a good strategy?)

- Basic setup: A hypothesis space (classifiers) and a calibration error
- Problem: Find a classifier which optimizes the calibration error

Learn a well-calibrated and accurate classifier (better?)

- **Basic setup**: A hypothesis space (classifiers) and an evaluation criterion
- **Basic setup (cont.)**: A hypothesis space (calibrators) and a calibration error
- **Problem**: Find an accurate classifier which optimizes the calibration error

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Post-hoc calibration methods

- assume a reasonably accurate pre-trained model is given,
- calibrate the soft/probabilistic output of the pre-trained model.





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- assume a reasonably accurate pre-trained model is given,
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Seek a (reasonably) accurate pre-trained model:

- a training (+ validation) data set,
- a hypothesis space (classifiers),
- an evaluation criterion,
- and a notion of an optimal classifier.





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Post-hoc calibration methods

- assume a reasonably accurate pre-trained model is given,
- calibrate the soft/probabilistic output of the pre-trained model.

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- a training (+ validation) data set,
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- an evaluation criterion,
- and a notion of an optimal classifier.

Seek a(n reasonably) good calibrator:

- a training (+ validation) data set,
- a hypothesis space (calibrators),
- an evaluation criterion,
- and a notion of an optimal calibrator.



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Empirical Binning

Basic Setup:

- Binary classification: $\mathscr{Y} := \{0, 1\}$
- Loss function: $\ell(y', y) = \mathbb{1}(y' \neq y)$
- Prediction: $y_{\ell}^{\boldsymbol{\theta}} = \mathbb{1}(\theta_y | \boldsymbol{x} > 0.5)$





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Steps:

- Apply equal-width binning to θ₁|**x** on **D**
- For each bin $\mathbf{B}_m \longrightarrow \text{use } \overline{y}(\mathbf{B}_m)$





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Empirical Binning (Exercise 7)

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Question: Empirical Binning optimizes binary-ECE(D)?





Platt Scaling

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Learn a logistic transformation of the classifier

$$P(y=1|\boldsymbol{x}) \approx \frac{1}{1+\exp(A(\boldsymbol{\theta}|\boldsymbol{x})+B)}$$
(14)

- Estimate A and B: fit the regressor via maximum likelihood
- Multi-class classification: Platt Scaling \leftarrow Platt Scaling + z
- z ∈ {One-vs-All, One-vs-One}





Isotonic Regression (The Same Basic Setup)

Fits a non-parametric isotonic regressor,

• which outputs a step-wise non-decreasing function $f|\mathbf{x}$

minimize
$$\sum_{(y,\boldsymbol{x})\in\boldsymbol{D}} (y-f|\boldsymbol{x})^2$$
 s.t. $f|\boldsymbol{x} \ge f|\boldsymbol{x} \text{ if } \boldsymbol{\theta}|\boldsymbol{x} \ge \boldsymbol{\theta}|\boldsymbol{x}'$ (15)







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$$\sum_{(y,\boldsymbol{x})\in\boldsymbol{D}} (y-f|\boldsymbol{x})^2 \quad \text{s.t.} \qquad f|\boldsymbol{x} \ge f|\boldsymbol{x} \text{ if } \boldsymbol{\theta}|\boldsymbol{x} \ge \boldsymbol{\theta}|\boldsymbol{x}' \quad (15)$$



An example of isotonic regression (solid red line)







Beta Calibration (The Same Basic Setup)

Learn a beta calibration map

$$P(y=1|\boldsymbol{x}) \approx \frac{1}{1 + 1/\left(\exp(c)\frac{(\theta|\boldsymbol{x})^{a}}{(1-\theta|\boldsymbol{x})^{b}}\right)}$$
(16)

There are some requirements [5]:

- each calibration is monotonically non-decreasing $\rightarrow a, b \ge 0$
- c is some real number





Practical Examples [6]

Beyond sigmoids with beta calibration





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Notes on Post-hoc Calibration (Homework)

Basic setup:

- Choose some calibration error
- Choose your favorite classifier
- · Choose one data set you want to work with







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- Compute the average 0/1 loss + calibration error
- Estimate the prior distribution $P(\mathscr{Y})$ using MLE and/or DM
- Use $h(\mathbf{x}) = P(\mathcal{Y}), \forall \mathbf{x}$
- Compute the average 0/1 loss + calibration error





Potential Impact [8]

Basic Setup:

- run 10×10-fold stratified cross-validation \longrightarrow average the results
- UC = The uncalibrated model (trained using the entire training set)
- PS = UC + Platt scaling (training set = 2/3 train + 1/3 calibration)
- VA = UC + Venn-Abers (training set = 2/3 train + 1/3 calibration)
- Compare Accuracy (1 0/1 loss) and Binary-ECE
- 25 data sets for binary classification





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- 25 data sets for binary classification

Classifiers:

- UC = RF: Random forest
- UC = xGBoost: Extreme Gradient Boosting





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Data set characteristics [8]

Data set	#instances	#features	Class distr.	Data set	#instances	#features	Class distr.
colic	375	59	134/223	kc2	369	21	270/99
creditA	690	42	383/307	kc3	325	39	283/42
diabetes	768	8	500/268	liver	341	6	142/199
german	955	27	283/672	pc1req	104	8	55/49
haberman	283	3	204/79	pc4	1343	37	1166/177
heartC	302	22	164/138	sonar	208	60	97/111
heartH	293	20	187/106	spect	218	22	24/194
heartS	270	13	150/120	spectf	267	44	55/212
hepatitis	155	19	123/32	transfusion	502	4	371/131
iono	350	33	225/125	ttt	958	27	332/626
je4042	270	8	136/134	vote	517	16	429/144
je4243	363	8	161/202	wbc	463	9	225/263
kc1	1192	21	877/315				







Accuracy [8]

	RF			xGB								
Data sets	UC	PS	VA	UC	PS	VA	kc1	.710	.717	.716	.691	.716
Data sets	00	15	14	00	13	VA	kc2	.781	.771	.769	.762	.753
colic	.838	.819	.818	.840	.832	.824	kc3	.849	.858	.848	.868	.868
creditA	.850	.849	.837	.845	.854	.832	liver	.718	.694	.683	.701	.686
diabetes	.763	.759	.753	.736	.736	.715	pc1req	.696	.622	.673	.615	.567
german	.665	.703	.703	.623	.704	.703	pc4	.896	.889	.888	.897	.887
haberman	.661	.721	.712	.587	.721	.721	sonar	.714	.677	.684	.736	.683
heartC	.833	.822	.814	.788	.778	.772	spect	.883	.890	.873	.858	.885
heartH	.793	.808	.784	.720	.771	.768	spectf	.803	.791	.793	.809	.779
heartS	.824	.816	.808	.807	.804	.793	transfusion	.655	.698	.694	.657	.699
hepati	.837	.829	.814	.800	.813	.768	ttt	.918	.893	.891	.874	.889
iono	.936	.929	.918	.909	.911	.914	vote	.819	.801	.814	.801	.776
je4042	.758	.729	.727	.704	.744	.756	wbc	.949	.941	.946	.929	.931
je4243	.626	.630	.618	.606	.642	.628	Mean	.791	.786	.783	.766	.777





Binary-ECE [8]

	RF			xGB									
Data sets		DC	VA	UC	PS	VA	kc1	.090	.049	.059	.177	.072	.0
	UC	rs					kc2	.073	.065	.020	.172	.042	.0
colic	.062	.031	.024	.093	.057	.036	kc3	.054	.037	.052	.085	.038	.0
creditA	.031	.025	.045	.098	.064	.061	liver	.042	.036	.020	.174	.030	.0
diabetes	.018	.049	.036	.162	.044	.046	pc1req	.079	.132	.116	.247	.096	.1
german	.091	.019	.007	.198	.009	.009	pc4	.030	.024	.010	.058	.037	.(
haberman	.144	.041	.043	.307	.068	.077	sonar	.066	.120	.124	.146	.164	.1
heartC	.042	.025	.031	.133	.047	.038	spect	.063	.054	.052	.097	.051	
heartH	.051	.036	.059	.183	.056	.074	spectf	.028	.052	.042	.148	.054	
heartS	.042	.073	.070	.118	.080	.076	transfusion	.204	.092	.118	.227	.074	
hepati	.039	.073	.075	.121	.077	.119	ttt	.157	.044	.037	.073	.074	
iono	.049	.041	.061	.067	.041	.071	vote	.088	.111	.096	.156	.146	
je4042	.056	.044	.037	.188	.074	.076	wbc	.027	.029	.047	.048	.023	
je4243	.091	.049	.047	.271	.052	.070	Mean	.069	.054	.053	.150	.063	J



PyCalib

Python library for classifier calibration

User installation

The PyCalib package can be installed from Pypi with the command

pip install pycalib

Documentation

The documentation can be found at https://classifier-calibration.github.io/PyCalib/

${\tt sklearn.calibration.CalibratedClassifierCV}$

class sklearn.calibration.CalibratedClassifierCV(estimator=None, *, method='sigmoid', cv=None, n_jobs=None, ensemble=True, base estimator='deprecated')

[source]



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Outline

Classifier Calibration

- o Introduction
- Notions
- Calibration Errors
- Post-hoc Calibration
- $_{\odot}\,$ Other methods
- Conformal Prediction







(Hopefully) Calibration During Training [10]

- Calibration error → a regularization term
- Mixup: regularization ≈ augmentation + label smoothing effect







(Hopefully) Calibration During Training [10]

- Calibration error → a regularization term
- Mixup: regularization ≈ augmentation + label smoothing effect
- Few others (see [10][section 5.6] and elsewhere)







A Regularization Approach [7]

Optimization problem should be described after declaring

- a training (+ validation) data set,
- a hypothesis space,
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- and a notion of an optimal classifier.







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- and a notion of an optimal classifier.
- (criterion) = (negative log-likelihood) + λ * (calibration error)
- (calibration error) should be trainable (differentiable, ...)







A Regularization Approach (cont.) [7]

Remark: ECE = Confidence-ECE

E#	Dataset	Model	EC	E	Accuracy		
			Baseline	MMCE	Baseline	MMCE	
1	MNIST	LeNet 5	0.5%	0.2%	99.24%	99.26%	
2	CIFAR 10	Resnet 50	4.3%	1.2%	93.1%	93.4%	
3	CIFAR 10	Resnet 110	4.6%	1.1%	93.7%	94.0%	
4	CIFAR 10	Wide Resnet 28-10	4.5%	1.6%	94.1%	94.2%	
5	CIFAR 100	Resnet 32	19.6%	6.9%	67.0%	67.7%	
6	CIFAR 100	Wide Resnet 28-10	15.0%	8.9%	74.0%	76.6%	
7	Birds CUB 200	Inception-v3	2.6%	2.3%	78.2%	77.9%	
8	20 Newsgroups	Global Pooling CNN	16.5%	6.5%	74.2%	73.9%	
9	IMDB Reviews	HAN	4.9%	0.4%	86.8%	86.3%	
10	SST Binary	Tree LSTM	7.4%	5.9%	88.6%	88.7%	
11	HAR time series	LSTM	7.6%	5.9%	89.4%	90.3%	



Outline



Classifier Calibration

Conformal Prediction

- \circ Notions
- Coverage Metrics
- Conformal Procedures





Outline



- Classifier Calibration
- Conformal Prediction
 Notions
 - Notions
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 - Conformal Procedures







Coverage as Another Notion of Calibration [1]



Figure 1: Prediction set examples on Imagenet. We show three progressively more difficult examples of the class for squirrel and the prediction sets (i.e., $C(X_{test}))$ generated by conformal prediction.







Coverage as Another Notion of Calibration [1]



Figure 1: Prediction set examples on Imagenet. We show three progressively more difficult examples of the class for squirrel and the prediction sets (i.e., $C(X_{test}))$ generated by conformal prediction.

General setting:

- We wish to produce a (possibly empty) **set-valued prediction** for each query instance.
- We wish to guarantee that the probability of covering the true class is bounded by the chosen significance level $\sigma \in [0, 1]$.







Marginal and Conditional Coverage



Figure 10: Prediction sets with various notions of coverage: no coverage, marginal coverage, or conditional coverage (at a level of 90%). In the marginal case, all the errors happen in the same groups and regions in X-space. Conditional coverage disallows this behavior, and errors are evenly distributed.







Population Level: Marginal Coverage

- Data set = D_{train} + D_{calibration} + D_{test}
- They are expected to come from the same distribution
- Learn a predictor (classifier/regressor) h using D_{train}







Population Level: Marginal Coverage

- Data set = $\mathbf{D}_{train} + \mathbf{D}_{calibration} + \mathbf{D}_{test}$
- They are expected to come from the same distribution
- Learn a predictor (classifier/regressor) h using D_{train}
- Use $\mathbf{D}_{\text{calibration}}$ and \mathbf{h} to construct for each $\mathbf{x}_{\text{test}} \in \mathbf{D}_{\text{test}}$ a $Y_{\text{test}} \subset \mathscr{Y}$ s.t.

$$1 - \alpha \le P(y_{\text{test}} \in Y_{\text{test}})$$

where $\alpha \in [0, 1]$ is a user-chosen error rate.







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Marginal Coverage (Exercise 8)

• Prove that if we always predict $Y_{\text{test}} := \mathscr{Y}$ we can always produce perfect conformal predictions w.r.t. the notion of marginal coverage with any chosen significance level $\sigma \in [0, 1]$.







Marginal Coverage (Exercise 8)

- Prove that if we always predict $Y_{\text{test}} := \mathscr{Y}$ we can always produce perfect conformal predictions w.r.t. the notion of marginal coverage with any chosen significance level $\sigma \in [0, 1]$.
- Prove that if we know the prior distribution $P(\mathcal{Y})$, we can always produce perfect conformal predictions w.r.t. the notion of marginal coverage with any chosen significance level $\sigma \in [0, 1]$.







Basic setup:

• Choose your favorite classifier + data set







Basic setup:

Choose your favorite classifier + data set

Compute & compare:

- Train your favorite classifier
- Apply the chosen conformal procedure (see next slides)
- Compute the coverage metrics with different *a*







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- Always return Y_{test} := 𝒴
- Compute the coverage metrics with different α





- Prior information → partition **D** into G groups **D**^g
- We then ask for group-balanced coverage

$$1 - \alpha \le P(y_{\text{test}} \in Y_{\text{test}} | \boldsymbol{x}_{\text{test}} \in \mathbf{D}^g), g = 1, \dots, G.$$
(17)





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Class-Conditional Conformal Prediction:

• Partition **D** into $|\mathcal{Y}|$ groups, one per class $y \in \mathcal{Y}$

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(18)





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Other examples:

- Group patients into demographic groups
- Group set-valued predictions into groups of equal cardinality







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Other examples:

- Group patients into demographic groups
- Group set-valued predictions into groups of equal cardinality

Comment (AOS4): Shouldn't we always predict $Y_{\text{test}} := \mathscr{Y}$?





Individual Level: Conditional Coverage

Problem: construct for each $\mathbf{x}_{test} \in \mathbf{D}_{test}$ a $Y_{test} \subset \mathcal{Y}$ s.t.

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Comments [1]:

- A stronger property than the marginal/group coverage
- In the most general case, conditional coverage is impossible to achieve [11]
- $\bullet \longrightarrow$ check how close our procedure comes to approximating it







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Comment (AOS4): Shouldn't we always predict $Y_{\text{test}} := \mathscr{Y}$?







Conformal Risk Control

We have constructed prediction sets that bound the miscoverage

$$P(y_{\text{test}} \in Y_{\text{test}}) \ge 1 - \alpha \equiv 1 - P(y_{\text{test}} \in Y_{\text{test}}) \le \alpha$$
(19)

$$\equiv P(y_{\text{test}} \not\in Y_{\text{test}}) \le \alpha \tag{20}$$

• We haven't taken into account the cardinality² $|Y_{test}|$



Uncertainty Reasoning and Machine Learning







Conformal Risk Control

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$$P(y_{\text{test}} \in Y_{\text{test}}) \ge 1 - \alpha \equiv 1 - P(y_{\text{test}} \in Y_{\text{test}}) \le \alpha$$
(19)

$$\equiv P(y_{\text{test}} \not\in Y_{\text{test}}) \le \alpha \tag{20}$$

- We haven't taken into account the cardinality² $|Y_{test}|$
- We can consider both the miscoverage and cardinality using

$$\ell(y_{\text{test}}, Y_{\text{test}})$$
 (21)

 \rightarrow any bounded loss function that shrinks as $|Y_{test}|$ grows.

We may construct prediction sets that bound the expected loss

$$\mathsf{E}\left[\ell(y_{\text{test}}, Y_{\text{test}}) | \boldsymbol{x}\right] = \sum_{y_{\text{test}} \in \mathscr{Y}} \ell(y_{\text{test}}, Y_{\text{test}}) * P(y_{\text{test}} | \boldsymbol{x}) \le \alpha$$
(22)

²Still remember $Y_{\text{test}} := \mathscr{Y}$?



Outline



- Classifier Calibration
- Conformal Prediction
 - \circ Notions
 - Coverage Metrics
 - Conformal Procedures







Population Level: Empirical Coverage³

• Empirical coverage (EC) metric is defined as

$$\mathsf{EC}\operatorname{-metric}(\mathbf{D}_{\mathsf{test}}) = \frac{1}{|\mathbf{D}_{\mathsf{test}}|} \sum_{\mathbf{x}_{\mathsf{test}} \in \mathbf{D}_{\mathsf{test}}} \mathbb{I}(y_{\mathsf{test}} \in Y_{;\mathsf{test}})$$
(23)

³Should we always predict $Y_{\text{test}} := \mathscr{Y}$?






Population Level: Empirical Coverage³

• Empirical coverage (EC) metric is defined as

$$\mathsf{EC}\operatorname{-metric}(\mathbf{D}_{\mathsf{test}}) = \frac{1}{|\mathbf{D}_{\mathsf{test}}|} \sum_{\mathbf{x}_{\mathsf{test}} \in \mathbf{D}_{\mathsf{test}}} \mathbb{1}(y_{\mathsf{test}} \in Y_{;\mathsf{test}})$$
(23)

If we consider

$$P(y_{\text{test}} \in Y_{\text{test}}) \longleftarrow \frac{1}{|\mathbf{D}_{\text{test}}|} \sum_{\mathbf{x}_{\text{test}} \in \mathbf{D}_{\text{test}}} \mathbb{I}(y_{\text{test}} \in Y_{\text{test}})$$
(24)

• then we might claim the relation

$$\mathsf{EC}\operatorname{-metric}(\mathbf{D}_{\mathsf{test}}) \le P(y_{\mathsf{test}} \in Y_{\mathsf{test}}) \tag{25}$$

³Should we always predict $Y_{\text{test}} := \mathscr{Y}$?



F



Group Level: Feature-Stratified Coverage Metric⁴

- Feature information \rightarrow partition **D** into *G* groups **D**^{*g*}
- Feature-stratified coverage (FSC) metric is defined as

$$FSC-metric(\mathbf{D}_{test}) = \min_{g \in \{1,...,G\}} \frac{1}{|\mathbf{D}_{test}^g|} \sum_{\mathbf{x}_{test} \in \mathbf{D}_{test}^g} \mathbb{1}(y_{test} \in Y_{test})$$
(26)

⁴Should we always predict $Y_{\text{test}} := \mathscr{Y}$?







Group Level: Feature-Stratified Coverage Metric⁴

- Feature information \rightarrow partition **D** into *G* groups **D**^{*g*}
- Feature-stratified coverage (FSC) metric is defined as

$$FSC-metric(\mathbf{D}_{test}) = \min_{g \in \{1,...,G\}} \frac{1}{|\mathbf{D}_{test}^g|} \sum_{\mathbf{x}_{test} \in \mathbf{D}_{test}^g} \mathbb{I}(y_{test} \in Y_{test})$$
(26)

• If we consider (the instances within each $\mathbf{D}^g_{\text{test}}$ equally and)

$$P(y_{\text{test}} \in Y_{\text{test}} | \boldsymbol{x}_{\text{test}}) \longleftarrow \frac{1}{|\boldsymbol{\mathsf{D}}_{\text{test}}^g|} \sum_{\boldsymbol{x}_{\text{test}} \in \boldsymbol{\mathsf{D}}_{\text{test}}^g} \mathbb{I}(y_{\text{test}} \in Y_{\text{test}})$$
(27)

• then we might claim the relation

$$FSC-metric(\mathbf{D}_{test}) \le P(y_{test} \in Y_{test} | \mathbf{x}_{test}), \forall \mathbf{x}_{test} \in \mathbf{D}_{test}$$
(28)

⁴Should we always predict $Y_{\text{test}} := \mathscr{Y}$?





Group Level: Size-Stratified Coverage Metric⁵

- Cardinality $|Y| \rightarrow \text{partition } \mathbf{D} \text{ into } G \text{ groups } \mathbf{D}^g$
- Size-Stratified Coverage (SSC) metric is defined as

$$SSC-metric(\mathbf{D}_{test}) = \min_{g \in \{1,...,G\}} \frac{1}{|\mathbf{D}_{test}^g|} \sum_{\mathbf{x}_{test} \in \mathbf{D}_{test}^g} \mathbb{I}(y_{test} \in Y_{test})$$
(29)

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- Cardinality $|Y| \rightarrow$ partition **D** into G groups \mathbf{D}^{g}
- Size-Stratified Coverage (SSC) metric is defined as

$$SSC-metric(\mathbf{D}_{test}) = \min_{g \in \{1,...,G\}} \frac{1}{|\mathbf{D}_{test}^g|} \sum_{\mathbf{x}_{test} \in \mathbf{D}_{test}^g} \mathbb{1}(y_{test} \in Y_{test})$$
(29)

If we consider the instances within each D^g_{test} equally and

$$P(y_{\text{test}} \in Y_{\text{test}} | \boldsymbol{x}_{\text{test}}) \approx \frac{1}{|\boldsymbol{\mathsf{D}}_{\text{test}}^{g}|} \sum_{\boldsymbol{x}_{\text{test}} \in \boldsymbol{\mathsf{D}}_{\text{test}}^{g}} \mathbb{I}(y_{\text{test}} \in Y_{\text{test}})$$
(30)

then we might claim the relation

$$SSC-metric(\mathbf{D}_{test}) \le P(y_{test} \in Y_{test} | \mathbf{x}_{test}), \forall \mathbf{x}_{test} \in \mathbf{D}_{test}$$
(31)

⁵Should we always predict $Y_{\text{test}} := \mathscr{Y}$?





Cover. Metrics Have often Been Coupled with Prediction Size

This can (hopefully) be done by using, for example,

- a loss considering both the miscoverage and cardinality,
- a suitable conformal procedure (see next slides),
- and so on.





Outline



- Classifier Calibration
- Conformal Prediction
 - \circ Notions
 - Coverage Metrics
 - Conformal Procedures







Split Conformal Prediction: Steps

- Learn a classifier h using D_{train}
- Define the score function $s(\mathbf{x}, \mathbf{y}) \in \mathbb{R}$, which should depend on **h**.
- Larger $s \rightarrow$ worse agreement between x and y.







Split Conformal Prediction: Steps

- Learn a classifier h using D_{train}
- Define the score function $s(\mathbf{x}, \mathbf{y}) \in \mathbb{R}$, which should depend on **h**.
- Larger $s \rightarrow$ worse agreement between x and y.
- Let *M* = |**D**_{validation}|, compute

$$s_1 = s(\boldsymbol{x}_1, y_1), \dots, s_M = s(\boldsymbol{x}_M, y_M), (\boldsymbol{x}_m, y_m) \in \mathbf{D}_{\text{validation}}$$

Sort the calibration scores s₁,..., s_M in the decreasing order
 Find (n+1)(1-α)/n quantile q_α of the calibration scores





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$$s_1 = s(x_1, y_1), \dots, s_M = s(x_M, y_M), (x_m, y_m) \in \mathbf{D}_{validation}$$

- Sort the calibration scores s_1, \ldots, s_M in the decreasing order
- Find $\frac{(n+1)(1-\alpha)}{n}$ quantile q_{α} of the calibration scores
- For any *x*_{test}, predict

$$Y_{\text{test}} = \left\{ y \in \mathscr{Y} \text{ s.t. } s(\boldsymbol{x}_{\text{test}}, y) \le q_{\alpha} \right\}$$
(32)





Split Conformal Prediction: A Marginal Coverage Seeker

Conformal coverage guarantee [1, 9]:

• Suppose (*x*_m, *y*_m) ∈ **D**_{validation} and (*x*_{test}, *y*_{test}) are independent and identically distributed (i.i.d.). Then the following holds:

$$1 - \alpha \le P(y_{\text{test}} \in Y_{\text{test}}) \tag{33}$$







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Assumptions:

- Larger $s \rightarrow$ worse agreement between x and y.
- $(\mathbf{x}_m, \mathbf{y}_m) \in \mathbf{D}_{\text{validation}}$ and $(\mathbf{x}_{\text{test}}, \mathbf{y}_{\text{test}})$ are independent i.i.d.







Assumptions of I.I.D.

Independence:

- The occurrence or value of one data point does not provide any information about the occurrence or value of another data point.
- The data points are not influenced by each other and that there is no hidden structure or correlation among them.







Assumptions of I.I.D.

Independence:

- The occurrence or value of one data point does not provide any information about the occurrence or value of another data point.
- The data points are not influenced by each other and that there is no hidden structure or correlation among them.

Identical distribution:

• The data points are drawn from the same underlying distribution.







Split Conformal Prediction: A Smallest Average Size Seeker

Average size [9][Remark 4] is defined as

$$E(Y) = \sum_{y \in \mathscr{Y}} P(y \in Y)$$
(34)









Conformal prediction can also be adapted to handle

- unsupervised outlier detection
- covariate/distribution shift
- multilabel classification







Remember to Check the Underlying Assumptions







github.com/aangelopoulos/conformal-prediction

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README.md
Conformal Prediction
rigorous uncertainty quantification for any machine learning task
paper arXiv website Berkeley conda env license MIT • Views 336 htts 8576

This repository is the easiest way to start using conformal prediction (a.k.a. conformal inference) on real data.





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