

Uncertainty reasoning and machine learning Introduction to notions of calibrated and valid predictions

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AOS4 master courses

[Uncertainty Reasoning and Machine Learning](#page-0-0)

A predictive system

● perceives **a training data set** (consisting of input-output pairs which specify individuals of a population) and **a hypothesis space** (consisting of the possible classifiers),

A predictive system

- perceives **a training data set** (consisting of input-output pairs which specify individuals of a population) and **a hypothesis space** (consisting of the possible classifiers),
- and seeks a classifier that **optimizes** its chance of making accurate predictions with respect to some given **evaluation criterion** (which is typically a loss function or an accuracy metric) which reflects how good/bad the predictive system is.

Optimization problem should be described after declaring

- \bullet a training (+ validation) data set,
- \bullet a hypothesis space,
- an evaluation criterion,
- and a notion of an optimal classifier.

Optimization Problem: "Spam in Emails" Example

What optimization problem do you want to solve?

• Using a decision tree to predict "Spam in Emails"

Optimization Problem: "Cat Dog classification" Example

What optimization problem do you want to solve?

• Using a convolutional neural network (CNN) to predict images as either a cat or a dog

After this lecture students should be able to

- describe commonly used notions of classifier calibration [\[10\]](#page-127-0)
- describe a few calibration errors and calibration methods [\[10\]](#page-127-0)
- describe commonly used notions of coverage [\[1\]](#page-126-0)
- describe a few coverage metrics and conformal procedures [\[1\]](#page-126-0)

Outline

[Classifier Calibration](#page-8-0)

- ❍ [Introduction](#page-9-0)
- ❍ [Notions](#page-16-0)
- ❍ [Calibration Errors](#page-30-0)
- ❍ [Post-hoc Calibration](#page-49-0)
- ❍ [Other methods](#page-76-0)
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- **[Classifier Calibration](#page-8-0)**
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A Weather Forecasting Example

A Weather Forecasting Example

- Forecaster: "the probability of rain tomorrow in Compiègne is 80%"
- How could we interpret this forecast?

A Weather Forecasting Example (cont.)

- \bullet On about 80% of the days when the whether conditions are like tomorrow's, you would experience rain in Compiègne?
- \bullet It will rain in 80% of the land area of Compiègne?
- \bullet It will rain in 80% of the time?

A Weather Forecasting Example (cont.)

- \bullet On about 80% of the days when the whether conditions are like tomorrow's, you would experience rain in Compiègne?
- \bullet It will rain in 80% of the land area of Compiègne?
- \bullet It will rain in 80% of the time?

Determining the degree to which a forecaster is well-calibrated

- cannot be done on a per-forecast basis,
- but requires looking at a sufficiently large and diverse set of forecasts.

Why Calibration Matters?

A well-calibrated classifier is expected to

• generate estimated class probabilities, which are consistent with what would naturally occur.

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A well-calibrated classifier is expected to

- generate estimated class probabilities, which are consistent with what would naturally occur.
- If (heterogeneous) classifiers can be well-calibrated,
	- their estimated class probabilities may be of the same "scale" and may be combined
	- they can be further compared given the same/similar levels of predictive performance.

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Notions of Calibration (Mentioned in Lecture 3)

Confidence calibration [\[3\]](#page-126-1):

$$
P(y = \arg \max_{y \in \mathcal{Y}} \theta_y | \mathbf{x} \text{ such that } \max_{y \in \mathcal{Y}} \theta_y | \mathbf{x} = \beta) = \beta, \forall \beta \in [0, 1]. \tag{1}
$$

Notions of Calibration (Mentioned in Lecture 3)

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$$

Classwise calibration [\[12\]](#page-127-1):

$$
P(y \text{ such that } \theta_y | \mathbf{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].
$$
 (2)

● May be harder to ensure, compared to **confidence calibration**

Notions of Calibration (Mentioned in Lecture 3)

Confidence calibration [\[3\]](#page-126-1):

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Classwise calibration [\[12\]](#page-127-1):

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P(y \text{ such that } \theta_y | \mathbf{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].
$$
 (2)

● May be harder to ensure, compared to **confidence calibration Distribution calibration** [\[4\]](#page-126-2):

$$
P(y \text{ such that } \theta | x = q) = q, \forall q \in \triangle^{|{\mathscr{Y}}|}, \tag{3}
$$

where $\Delta^{|\mathscr{Y}|}$ is the $|\mathscr{Y}|$ -dimensional simplex

● May be harder to ensure, compared to the **above notions**.

Notions of Calibration with Examples

(a) Underconfidence

(b) Overconfidence

(c) Calibrated classifier

Confidence calibration: Examples [\[2\]](#page-126-3)

Notions of Calibration with Examples (Exercise 1)

Basic setup (rephrased from an example in [\[10\]](#page-127-0)):

- A dataset contains 40 instances
- A model **h** which partitions the input space into 4 regions:

Notions of Calibration with Examples (Exercise 1)

Basic setup (rephrased from an example in [\[10\]](#page-127-0)):

- A dataset contains 40 instances
- A model **h** which partitions the input space into 4 regions:

Question: Check if the following statements are correct

- *h* is not confidence-calibrated
- *h* is classwise-calibrated
- *h* is not distribution-calibrated

Notions of Calibration with Examples (Solution 1.1)

Basic setup (rephrased from an example in [\[10\]](#page-127-0)):

Statement: *h* is not confidence-calibrated

$$
P(y = \arg \max_{y \in \mathcal{Y}} \theta_y | \mathbf{x} \text{ such that } \max_{y \in \mathcal{Y}} \theta_y | \mathbf{x} = \beta) = \beta, \forall \beta \in [0, 1]. \tag{4}
$$

•
$$
\beta = 0.4
$$
: $P = (4+3)/20 = 7/20 \neq 0.4$

•
$$
\beta = 0.6
$$
: $P = (5+7)/20 = 12/20 = 0.6$

Notions of Calibration with Examples (Solution 1.2)

Basic setup (rephrased from an example in [\[10\]](#page-127-0)):

Statement: *h* is classwise-calibrated

$$
P(y \text{ such that } \theta_y | \mathbf{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].
$$
 (5)

•
$$
y_1 \wedge \beta_1 = 0.3
$$
: $P = (2+4)/20 = 0.3$,

•
$$
y_2 \wedge \beta_2 = 0.3
$$
: $P = (2+4)/20 = 0.3$, $y_2 \wedge \beta_2 = 0.6$: $P = (5+7)/20 = 0.6$

•
$$
y_3 \wedge \beta_3 = 0.4
$$
: $P = 4/10 = 0.4$

•
$$
y_3 \wedge \beta_3 = 0.0
$$
: $P = 0/10 = 0.0$, $y_3 \wedge \beta_3 = 0.1$: $P = 1/10 = 0.1$

\n- \n
$$
y_1 \wedge \beta_1 = 0.3
$$
: \n $P = (2+4)/20 = 0.3$, \n $y_1 \wedge \beta_1 = 0.4$: \n $P = (3+5)/20 = 0.4$ \n
\n- \n $y_2 \wedge \beta_2 = 0.3$: \n $P = (2+4)/20 = 0.3$, \n $y_2 \wedge \beta_2 = 0.6$: \n $P = (5+7)/20 = 0.6$ \n
\n- \n $y_3 \wedge \beta_3 = 0.4$: \n $P = 4/10 = 0.4$, \n $y_3 \wedge \beta_3 = 0.3$: \n $P = 3/10 = 0.3$ \n
\n- \n $y_3 \wedge \beta_3 = 0.1$: \n $P = 1/10 = 0.1$ \n
\n

Notions of Calibration with Examples (Solution 1.3)

Basic setup (rephrased from an example in [\[10\]](#page-127-0)):

Statement: *h* is not distribution-calibrated

$$
P(y \text{ such that } \boldsymbol{\theta} | \mathbf{x} = \boldsymbol{q}) = \boldsymbol{q}, \forall \, \boldsymbol{q} \in \triangle^{|\mathcal{Y}|}, \tag{6}
$$

•
$$
\mathbf{q} = (0.3, 0.3, 0.4):
$$
 $P = (4/10, 2/10, 4/10) = (0.4, 0.2, 0.4) \neq (0.3, 0.3, 0.4)$

- $q = (0.4, 0.3, 0.3)$: $P = (3/10, 4/10, 3/10) = (0.3, 0.4, 0.3) \neq (0.4, 0.3, 0.3)$
- \bullet *q* = (0.4, 0.6, 0.0): *P* = (5/10, 5/10, 0/10) = (0.5, 0.5, 0.0) \neq (0.4, 0.6, 0.0)
- \bullet *q* = (0.3, 0.6, 0.1): *P* = (2/10, 7/10, 1/10) = (0.2, 0.7, 0.1) \neq (0.3, 0.6, 0.1)

A Note on Classifier Calibration (Exercise 2)

Consider three notions of classifier calibration:

• Confidence calibration [\[3\]](#page-126-1):

 $P(y = \arg \max_{y \in \mathcal{Y}} \theta_y | \mathbf{x} \text{ such that } \max_{y \in \mathcal{Y}} \theta_y | \mathbf{x} = \beta) = \beta, \forall \beta \in [0, 1].$ (7)

• Classwise calibration [\[12\]](#page-127-1):

$$
P(y \text{ such that } \theta_y | \mathbf{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].
$$
 (8)

Distribution calibration [\[4\]](#page-126-2):

$$
P(y \text{ such that } \theta | x = q) = q, \forall q \in \triangle^{|{\mathscr{Y}}|}, \tag{9}
$$

where $\Delta^{|\mathscr{Y}|}$ is the $|\mathscr{Y}|$ -dimensional simplex.

Prove that these notions are equivalent for binary classification?

A Note on Classifier Calibration (Exercise 3)

Consider three notions of classifier calibration:

• Confidence calibration [\[3\]](#page-126-1):

 $P(y = \arg \max_{y \in \mathcal{Y}} \theta_y | \mathbf{x} \text{ such that } \max_{y \in \mathcal{Y}} \theta_y | \mathbf{x} = \beta) = \beta, \forall \beta \in [0, 1].$ (10)

• Classwise calibration [\[12\]](#page-127-1):

$$
P(y \text{ such that } \theta_y | \mathbf{x} = \beta_y) = \beta_y, y \in \mathcal{Y}, \beta_y \in [0, 1].
$$
 (11)

• Distribution calibration [\[4\]](#page-126-2):

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P(y \text{ such that } \theta | x = q) = q, \forall q \in \triangle^{|{\mathscr{Y}}|}, \tag{12}
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• Confidence calibration [\[3\]](#page-126-1):

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where $\Delta^{|\mathscr{Y}|}$ is the $|\mathscr{Y}|$ -dimensional simplex.

Prove that $h(x) = P(\mathcal{Y})$, \forall **x**, is perfectly calibrated?

Notes on Classifier Calibration (Cont.)

Comments on confidence/classwise/distribution calibration:

- **Well-calibrated classifiers may perform poorly**.
- Using calibration error as the only criterion to assess classifiers might not be a good idea ...
- **Well-calibrated and accurate classifiers** would be useful in practice!
- They would be seen as **notions of marginal calibration** ←− **population level**

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Calibration Error: The Binary Case

Binary estimated calibration error (Binary-ECE):

- Specify a number *M* of bins
- Apply equal-width binning to $\theta_1|\mathbf{x}$ on **D**
- For each bin \mathbf{B}_m , compute average probability $\overline{s}(\mathbf{B}_m)$ and the proportion of positives $\bar{y}(\mathbf{B}_m)$

$$
\overline{s}(\mathbf{B}_{m}) = \frac{1}{|\mathbf{B}_{m}|} \sum_{\mathbf{x} \in \mathbf{B}_{m}} \theta_{1} | \mathbf{x}
$$

$$
\overline{y}(\mathbf{B}_{m}) = \frac{1}{|\mathbf{B}_{m}|} \sum_{\mathbf{x} \in \mathbf{B}_{m}} y
$$

● Compute Binary-ECE

Binary-ECE(**D**) =
$$
\sum_{m=1}^{M} \frac{|\mathbf{B}_{m}|}{|\mathbf{D}|} |\overline{y}(\mathbf{B}_{m}) - \overline{s}(\mathbf{B}_{m})|
$$

Calibration Error: The Binary Case (Exercise 4)

Basic setup:

- A given data set **D** = { (x_n, y_n) |*n* = 1,..., *N*} with *y* ∈ {0, 1}
- The proportion of instances with $y = 1$ is $0.5 + \epsilon$
- The decision rule is $0/1$ loss ℓ and the number of bins is 10

Questions:

• Show that there is at least one classifier with

Binary-ECE(**D**) = 0.0 and
$$
\frac{1}{N} \sum_{n=1}^{N} \ell(y_n^*, y_n) = 0.0
$$

Calibration Error: The Binary Case (Exercise 4)

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• Can we find worse perfectly calibrated classifiers?

Calibration Error: The Binary Case (Exercise 5)

Basic setup:

- A given data set **D** = { (x_n, y_n) |*n* = 1,..., *N*} with *y* ∈ {0, 1}
- The proportion of instances with $y = 1$ is $\alpha \neq 0.5$
- The decision rule is $0/1$ loss ℓ and the number of bins is M

Questions:

• Show that there is at least one classifier with

Binary-ECE(**D**) = 0.0 and
$$
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Calibration Error: The Binary Case (Exercise 5)

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$$
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Calibration Error: The Binary Case (Exercise 5)

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- A given data set **D** = { (x_n, y_n) |*n* = 1,..., *N*} with *y* ∈ {0, 1}
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• Can we find worse perfectly calibrated classifiers?

Classwise Calibration Error

Estimated classwise calibration error (classwise-ECE):

- For each class $y \in \mathcal{Y}$, consider y as class 1 and the others as 0
- Compute Binary-ECE for class *y* [∈] ^Y −→ Binary-ECE*^y* (**D**)
- Compute classwise-ECE

$$
\text{classeswise-ECE}(\mathbf{D}) = \frac{1}{|\mathcal{Y}|} \sum_{y \in \mathcal{Y}} \text{Binary-ECE}_y(\mathbf{D})
$$

Classwise Calibration Error (Exercise 6)

Basic setup:

- A given data set **D** = { (x_n, y_n) |*n* = 1, ..., *N*} with *y* ∈ {0, 1, 2}
- The proportions of instances with $(y = 0, y = 1, y = 2)$ are $(\alpha_0, \alpha_1, \alpha_2)$
- The decision rule is $0/1$ loss ℓ and the number of bins is M

Questions:

● Can we find at least one classifier with

classwise-ECE(**D**) = 0.0 and
$$
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• Show that there is at least one classifier with

classwise-ECE(**D**) = 0.0 and
$$
\frac{1}{N} \sum_{n=1}^{N} \ell(y_n^*, y_n) = 1 - \max(\alpha_0, \alpha_1, \alpha_2)
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Classwise Calibration Error (Exercise 6)

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$$

• Can we find worse perfectly calibrated classifiers?

Confidence Calibration Error

Confidence-ECE is the weighted average difference between accuracy and average confidence across all bins:

Confidence-ECE(**D**) =
$$
\sum_{m=1}^{M} \frac{|\mathbf{B}_m|}{|\mathbf{D}|} |\text{accuracy}(\mathbf{B}_m) - \text{confidence}(\mathbf{B}_m)|
$$
 (13)

- accuracy(\mathbf{B}_m): Average accuracy in bin \mathbf{B}_m
- confidence(\mathbf{B}_m): Average confidence in bin \mathbf{B}_m

Confidence Calibration Error (Exercise 7)

Basic setup:

- A given data set **D** = { (x_n, y_n) |*n* = 1, ..., *N*} with *y* ∈ {0, 1, 2}
- The proportions of instances with $(y = 0, y = 1, y = 2)$ are $(\alpha_0, \alpha_1, \alpha_2)$
- The decision rule is $0/1$ loss ℓ and the number of bins is M

Questions:

• Show that there is at least one classifier with

Confidence-ECE(D) = 0.0 and
$$
\frac{1}{N} \sum_{n=1}^{N} \ell(y_n^*, y_n) = 0.0
$$

Confidence Calibration Error (Exercise 7)

Basic setup:

- A given data set **D** = { (x_n, y_n) |*n* = 1, ..., *N*} with *y* ∈ {0, 1, 2}
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Confidence Calibration Error (Exercise 7)

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$$

• Can we find worse perfectly calibrated classifiers?

Notes on Classifier Errors (Homework)

Basic setup:

- Choose some calibration error
- Choose your favorite classifier
- Choose one data set you want to work with

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- Choose one data set you want to work with

Compute & compare:

- Train your favorite classifier
- Do post-hoc calibration (see next slides)
- Compute the calibration error

Notes on Classifier Errors (Homework)

Basic setup:

- Choose some calibration error
- Choose your favorite classifier
- Choose one data set you want to work with

Compute & compare:

- Train your favorite classifier
- Do post-hoc calibration (see next slides)
- Compute the calibration error
- Estimate the prior distribution $P(\mathscr{Y})$ using MLE and/or DM
- \bullet Use $h(x) = P(\mathscr{Y}), \forall x$
- Compute the calibration error

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How to learn well-calibrated and accurate classifiers1**?**

 1 I would be rich if I knew a very good answer :)

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Learn a well-calibrated classifier (a good strategy?)

- **Basic setup:** A hypothesis space (classifiers) and a calibration error
- **Problem**: Find a classifier which optimizes the calibration error

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Learn a well-calibrated and accurate classifier (better?)

- **Basic setup**: A hypothesis space (classifiers) and an evaluation criterion
- **Basic setup (cont.)**: A hypothesis space (calibrators) and a calibration error
- **Problem**: Find an accurate classifier which optimizes the calibration error

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Post-hoc calibration methods

- assume a reasonably accurate pre-trained model is given,
- calibrate the soft/probabilistic output of the pre-trained model.

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- and a notion of an optimal classifier.

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Seek a(n reasonably) **good calibrator**:

- \bullet a training (+ validation) data set,
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- \bullet an evaluation criterion.
- and a notion of an optimal calibrator.

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Empirical Binning

Basic Setup:

- Binary classification: $\mathscr{Y} := \{0, 1\}$
- **•** Loss function: $\ell(y', y) = \mathbb{I}(y' \neq y)$
- Prediction: y^θ_ℓ $\alpha_{\ell}^{\boldsymbol{\theta}} = \mathbb{1}(\theta_{\mathsf{y}} | \mathbf{x} > 0.5)$

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Steps:

- Apply equal-width binning to $\theta_1|\mathbf{x}$ on **D**
- For each bin $\mathbf{B}_m \longrightarrow \text{use } \overline{V}(\mathbf{B}_m)$

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Empirical Binning (Exercise 7)

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Question: Empirical Binning optimizes binary-ECE(**D**)?

Platt Scaling

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Learn a **logistic transformation** of the classifier

$$
P(y=1|\mathbf{x}) \approx \frac{1}{1 + \exp(A(\boldsymbol{\theta}|\mathbf{x}) + B)}
$$
(14)

- Estimate *A* and *B*: fit the regressor **via maximum likelihood**
- **Multi-class classification**: Platt Scaling ←− Platt Scaling + z
- z ∈ {One-vs-All,One-vs-One}

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Isotonic Regression (The Same Basic Setup)

Fits a **non-parametric isotonic regressor**,

● which outputs a step-wise non-decreasing function *f*|*x*

minimize
$$
\sum_{(y,\mathbf{x})\in\mathbf{D}} (y-f|\mathbf{x})^2
$$
 s.t. $f|\mathbf{x} \ge f|\mathbf{x}$ if $\theta|\mathbf{x} \ge \theta|\mathbf{x}'$ (15)

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$$
\text{minimize} \quad \sum
$$

$$
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$$

An example of isotonic regression (solid red line)

Beta Calibration (The Same Basic Setup)

Learn a **beta calibration map**

$$
P(y=1|\mathbf{x}) \approx \frac{1}{1 + 1/(\exp(c)\frac{(\theta|\mathbf{x})^{\beta}}{(1-\theta|\mathbf{x})^{\beta}})}
$$
(16)

There are some requirements [\[5\]](#page-126-0):

- each calibration is monotonically non-decreasing −→ *a*,*b* ≥ 0
- *c* is some real number

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Practical Examples [\[6\]](#page-126-1)

Notes on Post-hoc Calibration (Homework)

Basic setup:

- Choose some calibration error
- Choose your favorite classifier
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- Compute the average $0/1$ loss $+$ calibration error
- Estimate the prior distribution $P(\mathscr{Y})$ using MLE and/or DM
- \bullet Use $h(x) = P(\mathscr{Y}), \forall x$
- Compute the average $0/1$ loss $+$ calibration error

Potential Impact [\[8\]](#page-127-0)

Basic Setup:

- run 10×10-fold stratified cross-validation \rightarrow average the results
- \bullet UC = The uncalibrated model (trained using the entire training set)
- $PS = UC +$ Platt scaling (training set = 2/3 train + 1/3 calibration)
- $VA = UC + Venn-Abers (training set = 2/3 train + 1/3 calibration)$
- Compare Accuracy (1 0/1 loss) and Binary-ECE
- 25 data sets for binary classification

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Classifiers:

- \bullet UC = RF: Random forest
- \bullet UC = xGBoost: Extreme Gradient Boosting

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Data set characteristics [\[8\]](#page-127-0)

Accuracy [\[8\]](#page-127-0)

Binary-ECE [\[8\]](#page-127-0)

PyCalib

Python library for classifier calibration

User installation

The PyCalib package can be installed from Pypi with the command

pip install pycalib

Documentation

The documentation can be found at https://classifier-calibration.github.io/PyCalib/

sklearn.calibration.CalibratedClassifierCV

class sklearn.calibration.CalibratedClassifierCV(estimator=None, *, method='sigmoid', cv=None, n_jobs=None, ensemble=True, base_estimator='deprecated')

[source]

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Outline

[Classifier Calibration](#page-8-0)

- ❍ [Introduction](#page-9-0)
- ❍ [Notions](#page-16-0)
- ❍ [Calibration Errors](#page-30-0)
- ❍ [Post-hoc Calibration](#page-49-0)
- ❍ [Other methods](#page-76-0)
- [Conformal Prediction](#page-83-0)

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(Hopefully) Calibration During Training [\[10\]](#page-127-1)

- Calibration error $→$ a regularization term
- Mixup: regularization \approx augmentation + label smoothing effect

(Hopefully) Calibration During Training [\[10\]](#page-127-1)

- Calibration error \longrightarrow a regularization term
- Mixup: regularization \approx augmentation + label smoothing effect
- Few others (see [\[10\]](#page-127-1)[section 5.6] and elsewhere)

A Regularization Approach [\[7\]](#page-126-0)

Optimization problem should be described after declaring

- \bullet a training (+ validation) data set,
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- (criterion) = (negative log-likelihood) + λ ^{*} (calibration error)
- \bullet (calibration error) should be trainable (differentiable, ...)

A Regularization Approach (cont.) [\[7\]](#page-126-0)

Remark: ECE = Confidence-ECE

Outline

[Classifier Calibration](#page-8-0)

● [Conformal Prediction](#page-83-0)

- ❍ [Notions](#page-84-0)
- ❍ [Coverage Metrics](#page-106-0)
- ❍ [Conformal Procedures](#page-114-0)

Outline

- **[Classifier Calibration](#page-8-0)**
- [Conformal Prediction](#page-83-0) ❍ [Notions](#page-84-0)
	- ❍ [Coverage Metrics](#page-106-0)
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Coverage as Another Notion of Calibration [\[1\]](#page-126-1)

Figure 1: Prediction set examples on Imagenet. We show three progressively more difficult examples of the class for squirrel and the prediction sets (i.e., $\mathcal{C}(X_{\text{test}})$) generated by conformal prediction.

Coverage as Another Notion of Calibration [\[1\]](#page-126-1)

Figure 1: Prediction set examples on Imagenet. We show three progressively more difficult examples of the class for squirrel and the prediction sets (i.e., $\mathcal{C}(X_{\text{test}})$) generated by conformal prediction.

General setting:

- We wish to produce a (possibly empty) **set-valued prediction** for each query instance.
- We wish to guarantee that **the probability of covering the true class** is bounded by the chosen significance level $\sigma \in [0,1]$.

Marginal and Conditional Coverage

Figure 10: Prediction sets with various notions of coverage: no coverage, marginal coverage, or conditional coverage (at a level of 90%). In the marginal case, all the errors happen in the same groups and regions in X-space. Conditional coverage disallows this behavior, and errors are evenly distributed.

Population Level: Marginal Coverage

- Data set = $\mathbf{D}_{\text{train}} + \mathbf{D}_{\text{calibration}} + \mathbf{D}_{\text{test}}$
- They are expected to come from the same distribution
- Learn a predictor (classifier/regressor) **h** using **D**train

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1-\alpha \leq P(y_{test} \in Y_{test})
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where $\alpha \in [0,1]$ is a user-chosen error rate.

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Marginal Coverage (Exercise 8)

• Prove that if we always predict $Y_{test} = \mathscr{Y}$ we can always produce perfect conformal predictions w.r.t. the notion of marginal coverage with any chosen significance level $\sigma \in [0,1]$.

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- Prove that if we always predict $Y_{test} = \mathcal{Y}$ we can always produce perfect conformal predictions w.r.t. the notion of marginal coverage with any chosen significance level $\sigma \in [0,1]$.
- Prove that if we know the prior distribution $P(\mathscr{Y})$, we can always produce perfect conformal predictions w.r.t. the notion of marginal coverage with any chosen significance level $\sigma \in [0,1]$.

Basic setup:

• Choose your favorite classifier + data set

Basic setup:

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Compute & compare:

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- Always return $Y_{\text{test}} := \mathscr{Y}$
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Group Level: Group-Balanced Conformal Prediction

- Prior information −→ partition **D** into *G* groups **D** *g*
- We then ask for group-balanced coverage

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1 - \alpha \le P(y_{\text{test}} \in Y_{\text{test}} | \mathbf{x}_{\text{test}} \in \mathbf{D}^g), g = 1, ..., G.
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• Partition **D** into |��| groups, one per class *y* ∈ *�*

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Other examples:

- Group patients into demographic groups
- Group set-valued predictions into groups of equal cardinality

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Comment (AOS4): Shouldn't we always predict $Y_{\text{test}} := \mathcal{Y}$?

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Problem: construct for each $x_{test} \in D_{test}$ a $Y_{test} \subset \mathcal{Y}$ s.t.

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Comments [\[1\]](#page-126-1):

- A stronger property than the marginal/group coverage
- In the most general case, conditional coverage is impossible to achieve [\[11\]](#page-127-2)
- → check how close our procedure comes to approximating it

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Comment (AOS4): Shouldn't we always predict $Y_{\text{test}} = \mathcal{Y}$?

Conformal Risk Control

• We have constructed prediction sets that bound the miscoverage

$$
P(y_{\text{test}} \in Y_{\text{test}}) \ge 1 - \alpha \equiv 1 - P(y_{\text{test}} \in Y_{\text{test}}) \le \alpha \tag{19}
$$

$$
\equiv P(y_{\text{test}} \not\in Y_{\text{test}}) \le \alpha \tag{20}
$$

 \bullet We haven't taken into account the cardinality² | Y_{test}|

[Uncertainty Reasoning and Machine Learning](#page-0-0) 59 and 59

Conformal Risk Control

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\equiv P(y_{\text{test}} \not\in Y_{\text{test}}) \le \alpha \tag{20}
$$

- \bullet We haven't taken into account the cardinality² | Y_{test}|
- We can consider both the miscoverage and cardinality using

$$
\ell(y_{\text{test}}, Y_{\text{test}}) \tag{21}
$$

- → any bounded loss function that shrinks as $|Y_{test}|$ grows.
- We may construct prediction sets that bound the expected loss

$$
E[\ell(y_{\text{test}}, Y_{\text{test}})|\mathbf{x}] = \sum_{y_{\text{test}} \in \mathcal{Y}} \ell(y_{\text{test}}, Y_{\text{test}}) * P(y_{\text{test}}|\mathbf{x}) \le \alpha \tag{22}
$$

²Still remember $Y_{\text{test}} := \mathscr{Y}$?

Outline

- **[Classifier Calibration](#page-8-0)**
- **[Conformal Prediction](#page-83-0)**
	- ❍ [Notions](#page-84-0)
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Population Level: Empirical Coverage³

• Empirical coverage (EC) metric is defined as

$$
EC-metric(\mathbf{D}_{test}) = \frac{1}{|\mathbf{D}_{test}|} \sum_{\mathbf{x}_{test} \in \mathbf{D}_{test}} \mathbb{I}(y_{test} \in Y_{test})
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(23)

³Should we always predict $Y_{\text{test}} := \mathcal{Y}$?

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$$
(23)

● If we consider

$$
P(y_{\text{test}} \in Y_{\text{test}}) \longleftarrow \frac{1}{|\mathbf{D}_{\text{test}}|} \sum_{\mathbf{x}_{\text{test}} \in \mathbf{D}_{\text{test}}} \mathbb{1}(y_{\text{test}} \in Y_{\text{test}})
$$
(24)

 \bullet then we might claim the relation

$$
EC-metric(D_{test}) \le P(y_{test} \in Y_{test})
$$
 (25)

³Should we always predict $Y_{\text{test}} := \mathscr{Y}$?

Group Level: Feature-Stratified Coverage Metric⁴

- Feature information −→ partition **D** into *G* groups **D** *g*
- Feature-stratified coverage (FSC) metric is defined as

FSC-metric(
$$
\mathbf{D}_{\text{test}}
$$
) = min $g \in \{1, ..., G\}$ $\frac{1}{|\mathbf{D}_{\text{test}}^g|} \sum_{\mathbf{x}_{\text{test}} \in \mathbf{D}_{\text{test}}^g} \mathbb{1}(y_{\text{test}} \in Y_{\text{test}})$ (26)

⁴Should we always predict $Y_{\text{test}} := \mathcal{Y}$?

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 \bullet If we consider (the instances within each \mathbf{D}_test^g equally and)

$$
P(y_{\text{test}} \in Y_{\text{test}} | \mathbf{x}_{\text{test}}) \longleftarrow \frac{1}{|\mathbf{D}_{\text{test}}^g|} \sum_{\mathbf{x}_{\text{test}} \in \mathbf{D}_{\text{test}}^g} \mathbb{I}(y_{\text{test}} \in Y_{\text{test}})
$$
(27)

 \bullet then we might claim the relation

$$
FSC-metric\big(\textbf{D}_{test}\big) \leq \textit{P}\big(\textit{y}_{test} \in \textit{Y}_{test} | \textit{x}_{test}\big), \forall \textit{x}_{test} \in \textbf{D}_{test} \qquad \quad \textbf{(28)}
$$

⁴Should we always predict $Y_{\text{test}} := \mathscr{Y}$?

Group Level: Size-Stratified Coverage Metric⁵

- Cardinality |*Y*| −→ partition **D** into *G* groups **D** *g*
- Size-Stratified Coverage (SSC) metric is defined as

SSC-metric(
$$
\mathbf{D}_{\text{test}}
$$
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\mathbf{D}_{\text{test}}
$$
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 \bullet If we consider the instances within each $\mathbf{D}_{\text{test}}^g$ equally and

$$
P(y_{\text{test}} \in Y_{\text{test}} | \mathbf{x}_{\text{test}}) \approx \frac{1}{|\mathbf{D}_{\text{test}}^g|} \sum_{\mathbf{x}_{\text{test}} \in \mathbf{D}_{\text{test}}^g} \mathbb{1}(y_{\text{test}} \in Y_{\text{test}})
$$
(30)

 \bullet then we might claim the relation

$$
SSC\text{-}metric(\textbf{D}_{test}) \leq P(\textit{y}_{test} \in \textit{Y}_{test} | \textbf{x}_{test}), \forall \textbf{x}_{test} \in \textbf{D}_{test} \qquad (31)
$$

⁵Should we always predict $Y_{test} := \mathscr{Y}$?

Cover. Metrics Have often Been Coupled with Prediction Size

This can (hopefully) be done by using, for example,

- a loss considering both the miscoverage and cardinality,
- a suitable conformal procedure (see next slides),
- \bullet and so on.

Outline

[Classifier Calibration](#page-8-0)

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Split Conformal Prediction: Steps

- Learn a classifier **h** using **D**_{train}
- Define the score function $s(x, y) \in \mathbb{R}$, which should depend on **h**.
- Larger *s* −→ worse agreement between *x* and *y*.

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- Let $M = |D_{validation}|$, compute

$$
s_1 = s(\mathbf{x}_1, y_1), \ldots, s_M = s(\mathbf{x}_M, y_M), (\mathbf{x}_m, y_m) \in \mathbf{D}_{\text{validation}}
$$

• Sort the calibration scores s_1, \ldots, s_M in the decreasing order • Find $\frac{(n+1)(1-\alpha)}{n}$ quantile q_α of the calibration scores

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- Sort the calibration scores s_1, \ldots, s_M in the decreasing order
- Find $\frac{(n+1)(1-\alpha)}{n}$ quantile q_α of the calibration scores
- For any \mathbf{x}_{test} , predict

$$
Y_{\text{test}} = \{ y \in \mathcal{Y} \text{ s.t. } s(\mathbf{x}_{\text{test}}, y) \le q_{\alpha} \}
$$
 (32)

Split Conformal Prediction: A Marginal Coverage Seeker

Conformal coverage guarantee [\[1,](#page-126-0) [9\]](#page-127-0):

• Suppose $(\mathbf{x}_m, y_m) \in \mathbf{D}_{\text{validation}}$ and $(\mathbf{x}_{\text{test}}, y_{\text{test}})$ are independent and identically distributed (i.i.d.). Then the following holds:

$$
1 - \alpha \le P(y_{\text{test}} \in Y_{\text{test}}) \tag{33}
$$

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1 - \alpha \le P(y_{\text{test}} \in Y_{\text{test}}) \tag{33}
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Assumptions:

- Larger *s* −→ worse agreement between *x* and *y*.
- \bullet ($\mathbf{x}_m, \mathbf{y}_m$) $\in \mathbf{D}_{\text{validation}}$ and ($\mathbf{x}_{\text{test}}, \mathbf{y}_{\text{test}}$) are independent i.i.d.

Assumptions of I.I.D.

Independence:

- The occurrence or value of one data point does not provide any information about the occurrence or value of another data point.
- The data points are not influenced by each other and that there is no hidden structure or correlation among them.

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Independence:

- The occurrence or value of one data point does not provide any information about the occurrence or value of another data point.
- The data points are not influenced by each other and that there is no hidden structure or correlation among them.

Identical distribution:

 \bullet The data points are drawn from the same underlying distribution.

Split Conformal Prediction: A Smallest Average Size Seeker

Average size [\[9\]](#page-127-0)[Remark 4] is defined as

$$
E(Y) = \sum_{y \in \mathcal{Y}} P(y \in Y) \tag{34}
$$

Other procedures [\[1\]](#page-126-0)

Conformal prediction can also be adapted to handle

- unsupervised outlier detection
- covariate/distribution shift
- multilabel classification

Remember to Check the Underlying Assumptions

github.com/aangelopoulos/conformal-prediction

 $\mathrel{\mathop:}=$ **README.md**

Conformal Prediction

rigorous uncertainty quantification for any machine learning task

paper arXiv website Berkeley conda env license MIT **D** Views 33k hits 8576

This repository is the easiest way to start using conformal prediction (a.k.a. conformal inference) on real data.

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